that detect one of the boundary marks (M) between the images, the second sensor spaced from the first sensor a distance equal to a fraction of the cutting width; and

a microprocessor (12) in communication with said reading system and the second motor (9) and the third motor (5), the [microporcessor] microprocessor having stored therein a preset sequence of marks corresponding to the feature of the boundary marks (M), the microprocessor (12) processing a signal from the reading system, recognizing the feature of the boundary marks (M) and controlling the second and third motors (9, 5),

wherein the device is able to perform the cutting in two mutually orthogonal directions upon rotation of the substrate (1) through 90°.

REMARKS

The foregoing Amendment is being submitted for purposes of discussion and is not to be entered.

Respectfully submitted,

Valter Maddalon

_____ By:_____

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